OPTICAL FINGERPRINT DETECTION MECHANISM

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Inventor:

IGAKI SEIGO; others: 02

Applicant:

FUJITSU LTD

Classification:

- international:

G06F15/64; A61B5/117; G06F15/62

- european:

Application number:

JP19920043025 19920228

Priority number(s):

Abstract of JP5242230

PURPOSE:To improve the positioning precision between an optical system and an image pickup element by attaching the image pickup element to a printed circuit board with a positioning plate between them to make a light reception face and the printed circuit board accurately parallel.

CONSTITUTION: An image pickup element 14 is soldered to a printed circuit board 17 with a positioning plate 20 between them, and as the result, the light reception face of the image pickup element 14 is certainly parallel with the printed circuit board 17. Since a protective case 24 covering a light source 12 and the image pickup element 14 is fixed after being positioned to the positioning plate 20, the case 24 is parallel with the positioning plate 20; and consequently, arrangement of the image pickup element 14 and the case 24 is unequivocally determined. The positioning precision of a first parallel plane plate 30 placed on the case and a parallel plane plate 31 placed on this plate 30 is fixedly determined to the case 24.

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- (71)【出願人】

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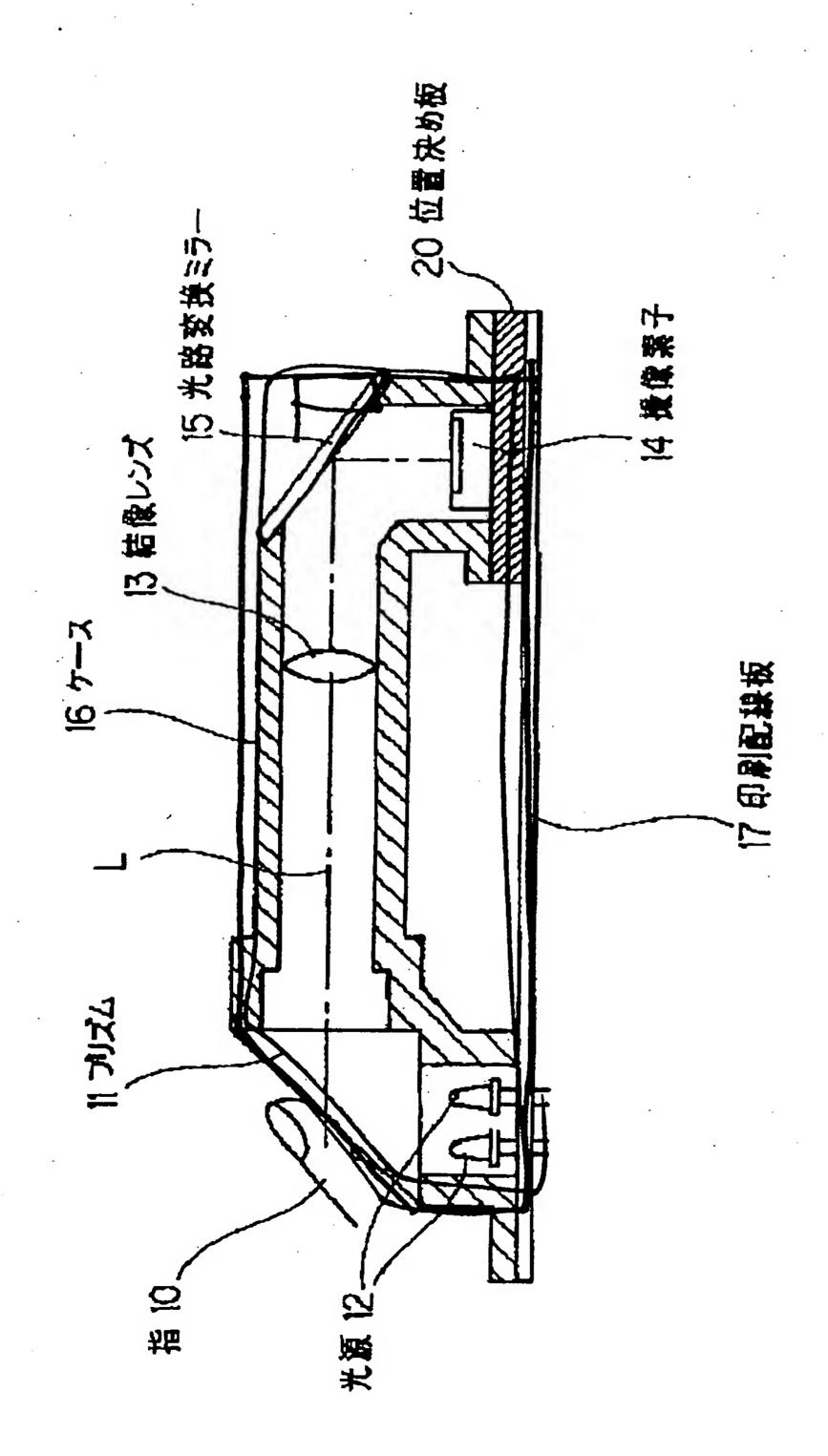
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本発明の第2の実施例を示す構成図





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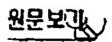
OPTICAL FINGERPRINT DETECTION MECHANISM

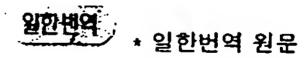
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우선권			

ABSTRACT

PURPOSE: To improve the positioning precision between an optical system and an image pickup element by attaching the image pickup element to a printed circuit board with a positioning plate between them to make a light reception face and the printed circuit board accurately parallel. CONSTITUTION: An image pickup element 14 is soldered to a printed circuit board 17 with a positioning plate 20 between them, and as the result, the light reception face of the image pickup element 14 is certainly parallel with the printed circuit board 17. Since a protective case 24 covering a light source 12 and the image pickup element 14 is fixed after being positioned to the positioning plate 20, the case 24 is parallel with the positioning plate 20; and consequently, arrangement of the image pickup element 14 and the case 24 is unequivocally determined. The positioning precision of a first parallel plane plate 30 placed on the case and a parallel plane plate 31 placed on this plate 30 is fixedly determined to the case 24.





* 데이터로딩 및 번역에 약 10-20초가 소요됩니다.

* 원문을 보시려면 원문 Viewer가 필요합니다. (다운받기)

